

Apéndice **C**

Programa

```

//-----
---
#include <vc1.h>
#pragma hdrstop

#include "Unit1.h"
#include <math.h>
#include "Unit2.h"
#include "Unit3.h"
#include "OpenGL.h"
//-----
---
#pragma package(smart_init)
#pragma link "VCap"
#pragma resource "*.dfm"
TForm1 *Form1;
//-----
---
__fastcall TForm1::TForm1(TComponent* Owner)
    : TForm(Owner)
{
}
//-----
---
void __fastcall TForm1::FormCreate(TObject * Sender)
{
    //mascara sobel 3x3
    sx[1][1]=-1.0;
    sx[1][2]=0.0;
    sx[1][3]=1.0;
    sx[2][1]=-2.0;
    sx[2][2]=0.0;
    sx[2][3]=2.0;
    sx[3][1]=-1.0;
    sx[3][2]=0.0;
    sx[3][3]=1.0;

    sy[1][1]=1.0;
    sy[1][2]=2.0;
    sy[1][3]=1.0;
    sy[2][1]=0.0;
    sy[2][2]=0.0;
    sy[2][3]=0.0;
    sy[3][1]=-1.0;
    sy[3][2]=-2.0;
    sy[3][3]=-1.0;
    //inicialización tamaño imagenes
    max_img_x=354;
    max_img_y=290;
    //inicialización pinta líneas detectadas de hough
    PintaBorde1->Checked=false; //dibuja vectores de transf
    hough
    FiltradoON->Checked=false; //realiza o no filtrado
    pasabajas
    BordeCanny1->Checked=true; //realiza detector de bordes
    canny o sobel
    Caracterist->Checked=true; //aparece resultado de
    coordenadas y matching en pantalla
    Sigmoidal->Checked=true; //habilita filtrado sigmoidal

    exponencial->Checked=false;
    polinomio->Checked=false;
    noajuste->Checked=true;
    //inicialización thresholds
    thres=40; //threshold binarización
    thres_h=5; //threshold tamaño de no muestras para
    hough
    thres_z=8; //threshold zonas de hough
    thres_c=5000;

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thres_s=128;
thres_cam=7;
thres_lin=8;
thres_mul=26;
//inicialización relleno canvas
Image1->Canvas->Brush->Color=c1Blue;
Image1->Canvas->FillRect(Rect(0,0,Image1->
Width,Image1->Height));
Image2->Canvas->Brush->Color=c1Blue;
Image2->Canvas->FillRect(Rect(0,0,Image2->
Width,Image2->Height));
Lienzo1->Canvas->Brush->Color=c1Black;
Lienzo1->Canvas->FillRect(Rect(0,0,Lienzo1->
Width,Lienzo1->Height));
Lienzo2->Canvas->Brush->Color=c1Black;
Lienzo2->Canvas->FillRect(Rect(0,0,Lienzo2->
Width,Lienzo2->Height));
Lienzo3->Canvas->Brush->Color=c1White;
Lienzo3->Canvas->FillRect(Rect(0,0,Lienzo3->
Width,Lienzo3->Height));
Lienzo4->Canvas->Brush->Color=c1White;
Lienzo4->Canvas->FillRect(Rect(0,0,Lienzo4->
Width,Lienzo4->Height));
//inicialización colores corregidos
r_cal_1=0.68;
g_cal_1=0.80;
b_cal_1=1.0;
r_cal_2=0.77;
g_cal_2=0.82;
b_cal_2=1.0;

a="ICM532A";
if (!Video->Init()) {
    ShowMessage(" Can't init capture!");
    Application->Terminate();
};
config = new TGraphConfig();
Video->SaveGraph(config);
config->Clear();

config->VCapSource=a;
config->WantPreview=true;
config->WantCapture=true;
config->WantBitmaps=true;
//config->CaptureFileName="aa.avi";
Video->RestoreGraph(config);
}
//-----
---
void __fastcall
TForm1::VideoBitmapGrabbed(TCapturedBitmap
*CapturedImage)
{
    CapturedImage->SaveToFile(nombre_foto);
    if(nombre_foto=="Img1.bmp")Image1->Picture-
>Assign(CapturedImage);
    if(nombre_foto=="Img2.bmp")Image2->Picture-
>Assign(CapturedImage);
}
//-----
---
void TForm1::accion1()
{
    a="ICM532A";

    Video->SaveGraph(config);
    config->VCapSource=a;
    Video->RestoreGraph(config);
}

```

```

Video->StartPreview();

nombre_foto="Img1.bmp";
Video->CaptureFrame();
}
//-----
---
void TForm1::accion2()
{
a="ICM532B";

Video->SaveGraph(config);
config->VCapSource=a;
Video->RestoreGraph(config);

Video->StartPreview();

nombre_foto="Img2.bmp";
Video->CaptureFrame();
}
//-----
---
void __fastcall TForm1::Threshold1Click(TObject * Sender)
{
Form2=new TForm2 (Application);
Form2->ShowModal();
delete Form2;
}
//-----
---
void __fastcall TForm1::DetenerClick(TObject
*Sender)//detiene captura
{
Timer1->Interval=0;
Timer2->Interval=0;

Detener->Enabled=false;
Accion1->Enabled=true;
}
//-----
---
void __fastcall TForm1::Accion1Click(TObject
*Sender)//inicia captura
{
Timer1->Interval=2500;
Sleep(1250);
Timer2->Interval=2500;

Detener->Enabled=true;
Accion1->Enabled=false;
}
//-----
---
void __fastcall TForm1::StartButtonClick(TObject *Sender)
{
Timer1->Interval=2500;
Sleep(1250);
Timer2->Interval=2500;

Detener->Enabled=true;
Accion1->Enabled=false;
}
//-----
-
void __fastcall TForm1::Timer2Timer(TObject *Sender)
{
accion2(); //toma la imagen 2
exponential_adj(2); //contraste
low_pass(2); //filtro difuminado
gray_borde_bin(2);
}

Hough(2); //si es igual a 1 mando a llamar algoritmo
2Dto3D (vectorizo)
color(2);
Matching(); //empalme de las imagenes
}
//-----
---
void __fastcall TForm1::Timer1Timer(TObject *Sender)
{
accion1(); //toma imagen 1
exponential_adj(1); //contraste
low_pass(1); //filtro difuminado
gray_borde_bin(1);
Hough(1); //vectoriza
color(1);
}
//-----
---
void TForm1::iniimg(TPicture* pBitmap,TPicture*
pBitmap2,int numero)//1 o 2 color
{
if(numero==1)pBitmap->Bitmap-
>LoadFromFile("Img1.bmp");
if(numero==2)pBitmap->Bitmap-
>LoadFromFile("Img2.bmp");

pBitmap2->Bitmap->LoadFromFile("aaa.bmp");

pBitmap->Bitmap->PixelFormat=pf24bit,pf24bit;
pBitmap2->Bitmap->PixelFormat=pf24bit,pf24bit;
}
//-----
---
void TForm1::iniimg2(TPicture* pBitmap,TPicture*
pBitmap2)//2 imagenes sobel
{
pBitmap->Bitmap->LoadFromFile("Img1s.bmp");
pBitmap2->Bitmap->LoadFromFile("Img2s.bmp");

pBitmap->Bitmap->PixelFormat=pf24bit,pf24bit;
pBitmap2->Bitmap->PixelFormat=pf24bit,pf24bit;
}
//-----
---
void TForm1::DrawLinea(int x,int y,int x1,int y1,float b,float
g,float r,TPicture* pBitmap,int canv)
{
int dx=x1-x;
int dy=y1-y;
int steps;
float xinc;
float yinc;
float xp=0,yp=0;

int xmax=pBitmap->Bitmap->Width;
int ymax=pBitmap->Bitmap->Height;
int cx=xmax/2;
int cy=ymax/2;

if((abs(dx))>=(abs(dy))) steps=abs(dx);
if((abs(dy))>(abs(dx))) steps=abs(dy);

if(canv==0)Lienzo->Canvas->Pixels[ cx+x][ymax-cy-
y]=(b*65536)+(g*256)+(r);
//if(canv==1)Lienzo1->Canvas->Pixels[cx+x][ymax-cy-
y]=(b*65536)+(g*256)+(r);
//if(canv==2)Lienzo2->Canvas->Pixels[cx+x][ymax-cy-
y]=(b*65536)+(g*256)+(r);
if(canv==3)Lienzo3->Canvas->Pixels[cx+x][ ymax-cy-
y]=(b*65536)+(g*256)+(r);
}

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//Errors->Lines->Add("X:" +IntToStr(x)+"
Y:" +IntToStr(y)+" | Angulo:" +FloatToStr(angulo2)+"
R:" +IntToStr(r));
if((r<600)&&(t>=0)&&(t<361)) //evita
desbordamiento
arreglo[t][r]++; //manda a arreglo
}
//-----
---
void TForm1::get_rt(int x,int y,float angulo,TPicture*
pBitmap)
{
float angulo2,x3,y3; //para hacer calculos en
flotante
int t,r;
int x2,y2;

angulo2=angulo+(M_PI/2.0); //obtiene angulo
perpendicular
if(angulo2>(M_PI+0.1)angulo2=angulo2-(M_PI); //para
trabajar solo con angulos positivos de 0 a 180

x2=floor((y-(x*tan(angulo)))/(tan(angulo2)-tan(angulo))+.5);
//obtiene coord x de coord. polar
x3=(y-(x*tan(angulo)))/(tan(angulo2)-tan(angulo));
//obtiene x flotante

y2=floor((x3*tan(angulo2))+.5); //obtiene y
y3=x3*tan(angulo2); //obtiene y flotante

if(x2==0)y2=y-((x)*tan(angulo)); //si x=0 se obtiene y
por otra formula

if((y2)>800)y2=800; //evita que y se diapore
if((y2)<-800)y2=-800;

//if((x2==0)&&(y2==0))y2=1;
r=sqrt((x3*x3)+(y3*y3)); //obtiene radio

if(y2<0.0)angulo2+=M_PI; //evita radios negativos
if((x>=0)&&(angulo>=(M_PI/2.0)-
0.2)&&(angulo<=(M_PI/2.0)+0.2))angulo2=0.0; //si hay lineas
verticales en x positivas las dibuja en polar como 0

t=floor((angulo2*180.0/(M_PI))+0.5); //angulo en rad a
grad para arreglo

//Errors->Lines->Add("X:" +IntToStr(x)+"
Y:" +IntToStr(y)+" | Angulo:" +FloatToStr(angulo2)+"
R:" +IntToStr(r));
rad=r;
tet=t;
}
//-----
---
int TForm1::diferencia(int x0i,int x1i,int x2i,int x0d,int x1d,int
x2d,int xi,int xd,int y,int menor)
{ //hace la diferencia entre 2 características
int result;
float inci,incd; //gurada angulo de características

//hacer un recorrido en las 30 casillas a ver cual es true
//indicando que ese es el angulo de ese pixel
for(int ciclo=1;ciclo<=thres_z*2;ciclo++)
{
if(s_arr[0][xi][y][ciclo-1]==true)
inci=((2.0*M_PI)/(thres_z*4))*ciclo;
if(s_arr[1][xd][y][ciclo-1]==true)
incd=((2.0*M_PI)/(thres_z*4))*ciclo;
}
}

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//result=abs(x1i-x1d)+abs(x0i-x0d)+abs(x2i-x2d);
//resultado tomando en cuenta el pixel central
//result=abs(x0i-x0d)+abs(x2i-x2d); //resultado sin tomar en
cuenta el pixel central y sin inclinacion
result=abs(x0i-x0d)+abs(x2i-x2d)+abs(inci-incd);//resultado
sin tomar en cuenta el pixel central CON inclinacion

return result;
}
//-----
---
void TForm1::dosDtotesD(TPicture* pBitmap)//coordenadas
2D a coordenadas 3D
{
float X,Y,Z;
int xr,xl,y;
int cx,cy;
int stereo_disp;
double sd;
float D=thres_cam;
float f=10.0;

//pBitmap->Bitmap->LoadFromFile("Img1.bmp");

Lienzo->Canvas->Brush->Color=clWhite;
Lienzo->Canvas->FillRect(Rect(0,0,Lienzo->Width,Lienzo-
>Height));
//dibuja ejes no es necesario correr ya lo posiciona
DrawLinea(100,0,-100,0,255,0,0,pBitmap,0);
DrawLinea(0,100,0,-100,255,0,0,pBitmap,0);

cy=pBitmap->Bitmap->Height/2;
cx=pBitmap->Bitmap->Width/2;

Errors->Lines->Add("----- 3D -----");
for(int ciclo1=0;ciclo1<ptr_pares;ciclo1++)//recorre arreglo
pares
{
xl=pares[ciclo1][0];
xr=pares[ciclo1][2];
y=pares[ciclo1][1];

stereo_disp=xl-xr;
if(stereo_disp>0)
{
sd=stereo_disp;
//convertir a coordenadas cartesianas
xl=xl-cx;
xr=xr-cx;
y=cy-y;
//formula X
X=floor(((D*(xr+xl))/(2.0*(xl-xr)))+.5);
//formula Y
Y=floor(((D*y)/(xl-xr))+0.5);
//formula Z
Z=floor(((7*650.0)/(xl-xr))+0.5);

if(thres_cam==7)
{
if(polinomio->Checked==true)
Z=470.787854-
(16.60765846*sd)+(0.268101545*pow(sd,2.0))+(-
0.002120258*pow(sd,3.0))+(-7.79504E-06*pow(sd,4.0))+(-
1.04632E-08*pow(sd,5.0));
if(exponencial->Checked==true)
Z=floor(((D*f)/(xl-xr))+0.5);
if(noajuste->Checked==true)
Z=floor(((7*575.0)/(xl-xr))+0.5);
}
}
}

```

```

if(thres_cam==10)
{
    if(polinomio->Checked==true)
        Z=933.7362657-
(30.63300217*sd)+(0.438465394*pow(sd,2.0))+(-
0.003084642*pow(sd,3.0))+(-1.03127E-05*pow(sd,4.0))+(-
1.28933E-08*pow(sd,5.0));
    if(exponencial->Checked==true)
        Z=floor(((D*f)/(x1-xr))+0.5);
    if(noajuste->Checked==true)
        Z=floor(((10*700.0)/(x1-xr))+0.5);
}
if(thres_cam==14)
{
    if(polinomio->Checked==true)
        Z=252.1291429-
(2.375071302*sd)+(0.003003327*pow(sd,2.0))+(-7.62778E-
05*pow(sd,3.0))+(-4.13927E-07*pow(sd,4.0))+(-6.17741E-
10*pow(sd,5.0));
    if(exponencial->Checked==true)
        Z=floor(((D*f)/(x1-xr))+0.5);
    if(noajuste->Checked==true)
        Z=floor(((14*620.0)/(x1-xr))+0.5);
}

//guarda coordenadas 3D
Coord3D[ciclo1][0]=X;
Coord3D[ciclo1][1]=Y;
Coord3D[ciclo1][2]=Z;
//no_coord=ptr_pares;

Errors->Lines->Add("X="+FloatToStr(X)+" | Y="+Y+"
| Z="+Z);
//dibuja donde se encuentra la X real
X=X*4.0;
Y=Y*4.0;
Z=Z*((double(thres_mul))/10.0);

DrawLinea(X-4,Y,X+4,Y,Z,Z,Z,pBitmap,0);
DrawLinea(X,Y-4,X,Y+4,Z,Z,Z,pBitmap,0); //color denota
profundidad
}
}
Status->SimpleText=FloatToStr(Z)+"=Z "+X+"=X
"+Y+"=Y "+ptr_pares+" puntero pares";
Status->SimpleText="Distancia entre
camaras="+FloatToStr(D)+" ";
Errors->Lines->SaveToFile("out.txt");
}
}
-----
---
void TForm1::color(int img)
{
    float a1,a2,a3,b1,b2,b3,f;
    float r=0.0,g=0.0,b=0.0;

    Graphics::TPicture *pBitmap = new Graphics::TPicture();
    Graphics::TPicture *pBitmap2 = new Graphics::TPicture();

    iniimg(pBitmap,pBitmap2,img);

    /* for (int y = 1; y < pBitmap->Bitmap->Height-1; y++)
    {
        ptr0 = (Byte *)pBitmap->Bitmap->ScanLine[y-1];
        ptr1 = (Byte *)pBitmap->Bitmap->ScanLine[y];
        ptr2 = (Byte *)pBitmap->Bitmap->ScanLine[y+1];

        ptr = (Byte *)pBitmap2->Bitmap->ScanLine[y];
        //ptr3 =(Byte *)pBitmap2->Bitmap->ScanLine[y-1];
        for (int x = 3; x < ((pBitmap->Bitmap->Width)*3)-3; x++)

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```

{
    //hace hough (deteccion de bordes)

    a1=(ptr0[x-
3]*sx[1][1]+ptr0[x]*sx[1][2]+ptr0[x+3]*sx[1][3]+ptr1[x-
3]*sx[2][1]+ptr1[x]*sx[2][2]+ptr1[x+3]*sx[2][3]+ptr2[x-
3]*sx[3][1]+ptr2[x]*sx[3][2]+ptr2[x+3]*sx[3][3]);
    a2=(ptr0[x-
2]*sx[1][1]+ptr0[x+1]*sx[1][2]+ptr0[x+4]*sx[1][3]+ptr1[x-
2]*sx[2][1]+ptr1[x+1]*sx[2][2]+ptr1[x+4]*sx[2][3]+ptr2[x-
2]*sx[3][1]+ptr2[x+1]*sx[3][2]+ptr2[x+4]*sx[3][3]);
    a3=(ptr0[x-
1]*sx[1][1]+ptr0[x+2]*sx[1][2]+ptr0[x+5]*sx[1][3]+ptr1[x-
1]*sx[2][1]+ptr1[x+2]*sx[2][2]+ptr1[x+5]*sx[2][3]+ptr2[x-
1]*sx[3][1]+ptr2[x+2]*sx[3][2]+ptr2[x+5]*sx[3][3]);

    b1=(ptr0[x-
3]*sy[1][1]+ptr0[x]*sy[1][2]+ptr0[x+3]*sy[1][3]+ptr1[x-
3]*sy[2][1]+ptr1[x]*sy[2][2]+ptr1[x+3]*sy[2][3]+ptr2[x-
3]*sy[3][1]+ptr2[x]*sy[3][2]+ptr2[x+3]*sy[3][3]);
    b2=(ptr0[x-
2]*sy[1][1]+ptr0[x+1]*sy[1][2]+ptr0[x+4]*sy[1][3]+ptr1[x-
2]*sy[2][1]+ptr1[x+1]*sy[2][2]+ptr1[x+4]*sy[2][3]+ptr2[x-
2]*sy[3][1]+ptr2[x+1]*sy[3][2]+ptr2[x+4]*sy[3][3]);
    b3=(ptr0[x-
1]*sy[1][1]+ptr0[x+2]*sy[1][2]+ptr0[x+5]*sy[1][3]+ptr1[x-
1]*sy[2][1]+ptr1[x+2]*sy[2][2]+ptr1[x+5]*sy[2][3]+ptr2[x-
1]*sy[3][1]+ptr2[x+2]*sy[3][2]+ptr2[x+5]*sy[3][3]);

    ptr[x]=sqrt(a1*a1+b1*b1);
    ptr[x+1]=sqrt(a2*a2+b2*b2);
    ptr[x+2]=sqrt(a3*a3+b3*b3);

    //Status->SimpleText="OK";
    //realiza binarizacion con threshold
    f=0.299*ptr[x+2]+0.587*ptr[x+1]+0.114*ptr[x];
    if(f<thres)
    {
    }
    else
    {
        r+=ptr1[x+2];
        g+=ptr1[x+1];
        b+=ptr1[x];
    }
}

x=x+2;
}
*/

//hace pasada a toda la imagen
for (int y = 1; y < pBitmap->Bitmap->Height-1; y++)
{
    Form1->ptr1 = (Byte *)pBitmap->Bitmap->ScanLine[y];

    //Form1->ptr2 = (Byte *)pBitmap2->Bitmap-
->ScanLine[y];

    for (int x = 3; x < ((pBitmap->Bitmap->Width)*3)-3; x++)
    {
        r+=Form1->ptr1[x+2];
        g+=Form1->ptr1[x+1];
        b+=Form1->ptr1[x];

        // r2+=Form1->ptr2[x+2];

```

```

// g2+=Form1->ptr2[x+1];
// b2+=Form1->ptr2[x];

x=x+2;
}
}
//Status->SimpleText="OK";
if(img==1)
{
R=r*r_cal_1;
G=g*g_cal_1;
B=b*b_cal_1;
}
if(img==2)
{
R2=r*r_cal_2;
G2=g*g_cal_2;
B2=b*b_cal_2;
}

Status->SimpleText="r="+FloatToStr(r)+" | g="+g+" |
b="+b+"R="+ R+" | G="+G+" | B="+B;
LienzoColor->Canvas->Brush->Color=clWhite;
R=(R+R2)/2.0;
G=(G+G2)/2.0;
B=(B+B2)/2.0;

if((R>(G+(thres_c*10)))&&(B>(G+(thres_c*10))))
LienzoColor->Canvas->Brush->Color=clPurple;
if((G>(R+(thres_c*10)))&&(B>(R+(thres_c*10))))
LienzoColor->Canvas->Brush->Color=clLime;
if((R>(B+(thres_c*10)))&&(G>(B+(thres_c*10))))
LienzoColor->Canvas->Brush->Color=clYellow;

if((R>(G+(thres_c*10)))&&(R>(B+(thres_c*10))))
LienzoColor->Canvas->Brush->Color=clRed;
if((G>(R+(thres_c*10)))&&(G>(B+(thres_c*10))))
LienzoColor->Canvas->Brush->Color=clGreen;
if((B>(R+(thres_c*10)))&&(B>(G+(thres_c*10))))
LienzoColor->Canvas->Brush->Color=clBlue;

LienzoColor->Canvas->FillRect(Rect(0,0,LienzoColor->
Width,LienzoColor->Height));

delete pBitmap;
delete pBitmap2;
}
-----
---
void TForm1::exponential_adj(int img) //ajuste exponencial
tipo sigmoidal
{
if(Sigmoidal->Checked==true)
{
Graphics::TPicture *pBitmap = new Graphics::TPicture();
Graphics::TPicture *pBitmap2 = new Graphics::TPicture();
float f;
int R,G,B;

iniimg(pBitmap,pBitmap2,img);

for (int y = 0; y < pBitmap->Bitmap->Height-1; y++)
{
ptr = (Byte *)pBitmap->Bitmap->ScanLine[y];

for (int x = 3; x < ((pBitmap->Bitmap->Width)*3)-3; x++)
{
//Errors->Lines->Add(ptr[x]);
//componentes rgb
R=ptr[x]*((1.0/(1.0+exp(-1*((ptr[x]-128.0)/thres_s)
)))+0.5);
G=ptr[x+1]*((1.0/(1.0+exp(-1*((ptr[x+1]-
128.0)/thres_s)))+0.5);
B=ptr[x+2]*((1.0/(1.0+exp(-1*((ptr[x+2]-
128.0)/thres_s)))+0.5);

if(R>255)R=255;
if(G>255)G=255;
if(B>255)B=255;

ptr[x]=R;
ptr[x+1]=G;
ptr[x+2]=B;

//ptr[x]=ptr[x]*(1.0/thres*.01);
//ptr[x+1]=ptr[x+1]*(1.0/thres*.01);
//ptr[x+2]=ptr[x+2]*(1.0/thres*.01);

x=x+2;
}
}
if(img==1)
{
Image1->Canvas->Draw(0,0,pBitmap->Bitmap);
Image1->Repaint();
pBitmap->SaveToFile("Img1.bmp");
}
if(img==2)
{
Image2->Canvas->Draw(0,0,pBitmap->Bitmap);
Image2->Repaint();
pBitmap->SaveToFile("Img2.bmp");
}
delete pBitmap;
delete pBitmap2;
}
}
-----
-
void TForm1::low_pass(int img) //filtrado smoothing
{
float mask[5][5];

if(FiltradoON->Checked==true)
{
if(Gaussiano->Checked==true) //realiza filtrado gaussiano
{
Graphics::TPicture *pBitmap = new Graphics::TPicture();
Graphics::TPicture *pBitmap2 = new Graphics::TPicture();
int arreglo[9],tmp;
//iniimg(pBitmap,pBitmap2);
iniimg(pBitmap,pBitmap2,img);

for (int y = 1; y < pBitmap->Bitmap->Height-1; y++)
{
ptr0 = (Byte *)pBitmap->Bitmap->ScanLine[y-1];
ptr = (Byte *)pBitmap->Bitmap->ScanLine[y];
ptr2 = (Byte *)pBitmap->Bitmap->ScanLine[y+1];

ptr1 = (Byte *)pBitmap2->Bitmap->ScanLine[y];

```

```

for (int x = 3; x < ((pBitmap->Bitmap->Width)*3)-3;
x++)
{
for(int color=0;color<3;color++)//ciclo para cada color
{

arreglo[0]=ptr0[x-3+color];
arreglo[1]=ptr0[x+color];
arreglo[2]=ptr0[x+3+color];
arreglo[3]=ptr[x-3+color];
arreglo[4]=ptr[x+color];
arreglo[5]=ptr[x+3+color];
arreglo[6]=ptr2[x-3+color];
arreglo[7]=ptr2[x+color];
arreglo[8]=ptr2[x+3+color];

for(int cic1=0;cic1<9;cic1++)
{
for(int cic2=0;cic2<9;cic2++)
{
if(arreglo[cic1]>arreglo[cic2])//realiza ordenamiento
p/mediana
{
tmp=arreglo[cic1];
arreglo[cic1]=arreglo[cic2];
arreglo[cic2]=tmp;
}
}
}
ptr1[x+color]=arreglo[4];
} //fin color
x=x+2;
} //x
} //y

if(img==1)
{
Image1->Canvas->Draw(0,0,pBitmap->Bitmap);
Image1->Repaint();
pBitmap2->SaveToFile("Img1.bmp");
}
if(img==2)
{
Image2->Canvas->Draw(0,0,pBitmap->Bitmap);
Image2->Repaint();
pBitmap2->SaveToFile("Img2.bmp");
}

delete pBitmap;
delete pBitmap2;
}

else //si no es activo filtrado gaussiano hace pasabajas
{
mask[1][1]=1.0/16.0;
mask[1][2]=1.0/8.0;
mask[1][3]=1.0/16.0;
mask[2][1]=1.0/8.0;
mask[2][2]=1.0/4.0;
mask[2][3]=1.0/8.0;
mask[3][1]=1.0/16.0;
mask[3][2]=1.0/8.0;
mask[3][3]=1.0/16.0;

Graphics::TPicture *pBitmap = new Graphics::TPicture();
Graphics::TPicture *pBitmap2 = new Graphics::TPicture();
iniimg(pBitmap,pBitmap2,img);
}

```

```

for (int y = 1; y < pBitmap->Bitmap->Height-1; y++)
{

ptr0 = (Byte *)pBitmap->Bitmap->ScanLine[y-1];
ptr = (Byte *)pBitmap->Bitmap->ScanLine[y];
ptr2 = (Byte *)pBitmap->Bitmap->ScanLine[y+1];

for (int x = 3; x < ((pBitmap->Bitmap->Width)*3)-3;
x++)
{
ptr[x]=floor(ptr0[x-
3]*mask[1][1]+ptr0[x]*mask[1][2]+ptr0[x+3]*mask[1][3]+ptr
[x-
3]*mask[2][1]+ptr[x]*mask[2][2]+ptr[x+3]*mask[2][3]+ptr2[
x-
3]*mask[3][1]+ptr2[x]*mask[3][2]+ptr2[x+3]*mask[3][3]+.5);
ptr[x+1]=floor(ptr0[x-
2]*mask[1][1]+ptr0[x+1]*mask[1][2]+ptr0[x+4]*mask[1][3]+
ptr[x-
2]*mask[2][1]+ptr[x+1]*mask[2][2]+ptr[x+4]*mask[2][3]+ptr
2[x-
2]*mask[3][1]+ptr2[x+1]*mask[3][2]+ptr2[x+4]*mask[3][3]+.
5);
ptr[x+2]=floor(ptr0[x-
1]*mask[1][1]+ptr0[x+2]*mask[1][2]+ptr0[x+5]*mask[1][3]+
ptr[x-
1]*mask[2][1]+ptr[x+2]*mask[2][2]+ptr[x+5]*mask[2][3]+ptr
2[x-
1]*mask[3][1]+ptr2[x+2]*mask[3][2]+ptr2[x+5]*mask[3][3]+.
5);

x=x+2;
}
}
if(img==1)
{
Image1->Canvas->Draw(0,0,pBitmap->Bitmap);
Image1->Repaint();
pBitmap->SaveToFile("Img1.bmp");
}
if(img==2)
{
Image2->Canvas->Draw(0,0,pBitmap->Bitmap);
Image2->Repaint();
pBitmap->SaveToFile("Img2.bmp");
}
delete pBitmap;
delete pBitmap2;
}
}
//-----
---

void TForm1::gray_borde_bin(int img)
{
float a1,a2,a3,b1,b2,b3,f;
int sector;

Graphics::TPicture *pBitmap = new Graphics::TPicture();
Graphics::TPicture *pBitmap2 = new Graphics::TPicture();
Graphics::TPicture *pBitmap3 = new Graphics::TPicture();
iniimg(pBitmap,pBitmap2,img);
//escala de grises
for (int y = 0; y < pBitmap->Bitmap->Height-1; y++)
{
ptr = (Byte *)pBitmap->Bitmap->ScanLine[y];
for (int x = 0; x < ((pBitmap->Bitmap->Width)*3)-3; x++)

```



```

{
//componentes rgb
f=0.299*ptr[x+2]+0.587*ptr[x+1]+0.114*ptr[x];
ptr[x]=floor(f+0.5);
ptr[x+1]=floor(f+0.5);
ptr[x+2]=floor(f+0.5); /*/

x=x+2;
}
}
if(img==1)
{
//Lienzo3->Canvas->Draw(0,0,pBitmap->Bitmap);
pBitmap->SaveToFile("Img1g.bmp");
}
if(img==2)
{
//Lienzo4->Canvas->Draw(0,0,pBitmap->Bitmap);
pBitmap->SaveToFile("Img2g.bmp");
}

//Sobel (deteccion de bordes) con imagen en gris
if(BordeCanny1->Checked==false)
{
for (int y = 1; y < pBitmap->Bitmap->Height-1; y++)
{
ptr0 = (Byte *)pBitmap->Bitmap->ScanLine[y-1];
ptr1 = (Byte *)pBitmap->Bitmap->ScanLine[y];
ptr2 = (Byte *)pBitmap->Bitmap->ScanLine[y+1];

ptr = (Byte *)pBitmap2->Bitmap->ScanLine[y];
ptr3 = (Byte *)pBitmap2->Bitmap->ScanLine[y-1];
for (int x = 3; x < ((pBitmap->Bitmap->Width)*3)-3; x++)
{
a1=(ptr0[x-
3]*sx[1][1]+ptr0[x]*sx[1][2]+ptr0[x+3]*sx[1][3]+ptr1[x-
3]*sx[2][1]+ptr1[x]*sx[2][2]+ptr1[x+3]*sx[2][3]+ptr2[x-
3]*sx[3][1]+ptr2[x]*sx[3][2]+ptr2[x+3]*sx[3][3]);
a2=(ptr0[x-
2]*sx[1][1]+ptr0[x+1]*sx[1][2]+ptr0[x+4]*sx[1][3]+ptr1[x-
2]*sx[2][1]+ptr1[x+1]*sx[2][2]+ptr1[x+4]*sx[2][3]+ptr2[x-
2]*sx[3][1]+ptr2[x+1]*sx[3][2]+ptr2[x+4]*sx[3][3]);
a3=(ptr0[x-
1]*sx[1][1]+ptr0[x+2]*sx[1][2]+ptr0[x+5]*sx[1][3]+ptr1[x-
1]*sx[2][1]+ptr1[x+2]*sx[2][2]+ptr1[x+5]*sx[2][3]+ptr2[x-
1]*sx[3][1]+ptr2[x+2]*sx[3][2]+ptr2[x+5]*sx[3][3]);

b1=(ptr0[x-
3]*sy[1][1]+ptr0[x]*sy[1][2]+ptr0[x+3]*sy[1][3]+ptr1[x-
3]*sy[2][1]+ptr1[x]*sy[2][2]+ptr1[x+3]*sy[2][3]+ptr2[x-
3]*sy[3][1]+ptr2[x]*sy[3][2]+ptr2[x+3]*sy[3][3]);
b2=(ptr0[x-
2]*sy[1][1]+ptr0[x+1]*sy[1][2]+ptr0[x+4]*sy[1][3]+ptr1[x-
2]*sy[2][1]+ptr1[x+1]*sy[2][2]+ptr1[x+4]*sy[2][3]+ptr2[x-
2]*sy[3][1]+ptr2[x+1]*sy[3][2]+ptr2[x+4]*sy[3][3]);
b3=(ptr0[x-
1]*sy[1][1]+ptr0[x+2]*sy[1][2]+ptr0[x+5]*sy[1][3]+ptr1[x-
1]*sy[2][1]+ptr1[x+2]*sy[2][2]+ptr1[x+5]*sy[2][3]+ptr2[x-
1]*sy[3][1]+ptr2[x+2]*sy[3][2]+ptr2[x+5]*sy[3][3]);

ptr[x]=sqrt(a1*a1+b1*b1);
ptr[x+1]=sqrt(a2*a2+b2*b2);
ptr[x+2]=sqrt(a3*a3+b3*b3);

//anula cuadro blanco del rededor
if((x<8)||(x>((pBitmap->Bitmap->Width)*3)-9))//lineas
verticales
{
ptr[x-3]=1;
ptr[x-2]=1;

ptr[x-1]=1;
ptr[x]=1;
ptr[x+1]=1;
ptr[x+2]=1;
}
}

final
{
ptr[x]=1;
ptr[x+1]=1;
ptr[x+2]=1;
}

//realiza binarizacion con threshold

f=0.299*ptr[x+2]+0.587*ptr[x+1]+0.114*ptr[x];
if(f<thres)
{
ptr[x]=1;
ptr[x+1]=1;
ptr[x+2]=1;
}
else
{
ptr[x]=255;
ptr[x+1]=255;
ptr[x+2]=255;
}
x=x+2;
} //fin x
} //fin y

//imagen con sobel y binarizada salva a archivo y dibuja
if(img==1)
{
Lienzo1->Canvas->Draw(0,0,pBitmap2->Bitmap);
pBitmap2->SaveToFile("Img1s.bmp");
}
if(img==2)
{
Lienzo2->Canvas->Draw(0,0,pBitmap2->Bitmap);
pBitmap2->SaveToFile("Img2s.bmp");
}
} //termina sobel

//canny (deteccion de bordes) con imagen en gris
if(BordeCanny1->Checked==true)
{
for (int y = 1; y < pBitmap->Bitmap->Height-1; y++)
{
ptr0 = (Byte *)pBitmap->Bitmap->ScanLine[y-1];
ptr1 = (Byte *)pBitmap->Bitmap->ScanLine[y];
ptr2 = (Byte *)pBitmap->Bitmap->ScanLine[y+1];

ptr = (Byte *)pBitmap2->Bitmap->ScanLine[y];
for (int x = 3; x < ((pBitmap->Bitmap->Width)*3)-3; x++)
{
//hace canny con mascara
a1=(ptr1[x+3]-ptr1[x]+ptr2[x+3]-ptr2[x]);
b1=(ptr1[x]-ptr2[x]+ptr1[x+3]-ptr2[x+3]);

```

```

ptr[x]=sqrt(a1*a1+b1*b1);
ptr[x+1]=ptr[x];
ptr[x+2]=ptr[x];

if(a1<=0.2)a1=0.2;
f=atan2(b1,a1);
//sectoriza
if((f<=M_PI)&&(f>7*M_PI/8))sector=0;
if((f<=7*M_PI/8)&&(f>5*M_PI/8))sector=3;
if((f<=5*M_PI/8)&&(f>3*M_PI/8))sector=2;
if((f<=2*M_PI/8)&&(f>M_PI/8))sector=1;

if((f<=M_PI/8)&&(f>-1*M_PI/8))sector=0;
if((f<=-1*M_PI/8)&&(f>-3*M_PI/8))sector=3;
if((f<=-3*M_PI/8)&&(f>-5*M_PI/8))sector=2;
if((f<=-5*M_PI/8)&&(f>-7*M_PI/8))sector=1;
if((f<=-7*M_PI/8)&&(f>M_PI))sector=0;

ptr1[x]=sector*1;
ptr1[x+1]=sector*1;
ptr1[x+2]=sector*1;
//anula cuadro blanco del rededor
if((x<8)||x>(pBitmap->Bitmap->Width)*3-9)//lineas
verticales
{
ptr[x-3]=1;
ptr[x-2]=1;
ptr[x-1]=1;
ptr[x]=1;
ptr[x+1]=1;
ptr[x+2]=1;
}
if(y<5) //horizontales del inicio
{
ptr[x]=1;
ptr[x+1]=1;
ptr[x+2]=1;
}
if(y>=pBitmap->Bitmap->Height-3) //horizontales del
final
{
ptr[x]=1;
ptr[x+1]=1;
ptr[x+2]=1;
}

x=x+2;
} //fin x
} //fin y

if(img==1)
{
Lienzo1->Canvas->Draw(0,0,pBitmap2->Bitmap);
pBitmap2->SaveToFile("Img1s.bmp");
pBitmap->SaveToFile("Almg1.bmp");
}
if(img==2)
{
Lienzo2->Canvas->Draw(0,0,pBitmap2->Bitmap);
pBitmap2->SaveToFile("Img2s.bmp"); //imagen de bordes
pBitmap->SaveToFile("Almg2.bmp"); //imagen de
angulos
}

//salva a imagenes temporales de canny
if(img==1)pBitmap2->SaveToFile("ImgC1.bmp");
if(img==2)pBitmap2->SaveToFile("ImgC2.bmp");
//realiza binarizacion con threshold pero
//con los 2 pixeles en línea

```

```

if(img==1)pBitmap3->Bitmap-
>LoadFromFile("Img1s.bmp");
if(img==2)pBitmap3->Bitmap-
>LoadFromFile("Img2s.bmp");

for (int y = 1; y < pBitmap->Bitmap->Height-1; y++)
{
ptr0 = (Byte *)pBitmap2->Bitmap->ScanLine[y-1];
//contienen los bordes
ptr1 = (Byte *)pBitmap2->Bitmap->ScanLine[y];
ptr2 = (Byte *)pBitmap2->Bitmap->ScanLine[y+1];

ptr = (Byte *)pBitmap->Bitmap->ScanLine[y]; //contiene
el sector
ptr3 = (Byte *)pBitmap3->Bitmap->ScanLine[y];
//deposita imagen final
for (int x = 3; x < ((pBitmap->Bitmap->Width)*3)-3; x++)
{
sector=ptr[x];

ptr3[x]=1;
ptr3[x+1]=1;
ptr3[x+2]=1;
if(sector==0)
{
if((ptr1[x]>ptr1[x-
3])&&(ptr1[x]>ptr1[x+3])&&(ptr1[x]>thres))//si el medio es
mas grande bueno

//if((ptr1[x]>ptr0[x])&&(ptr1[x]>ptr2[x])&&(ptr1[x]>thres))//
si el medio es mas grande
{
ptr3[x]=255;
ptr3[x+1]=255;
ptr3[x+2]=255;
}
else
{
ptr3[x]=1;
ptr3[x+1]=1;
ptr3[x+2]=1;
}
}
if(sector==1)
{
if((ptr1[x]>ptr2[x-
3])&&(ptr1[x]>ptr0[x+3])&&(ptr1[x]>thres))//si el medio es
mas grande
//if((ptr1[x]>ptr0[x-
3])&&(ptr1[x]>ptr2[x+3])&&(ptr1[x]>thres))//si el medio es
mas grande
{
ptr3[x]=255;
ptr3[x+1]=255;
ptr3[x+2]=255;
}
else
{
ptr3[x]=1;
ptr3[x+1]=1;
ptr3[x+2]=1;
}
}
if(sector==2)
{
if(((ptr1[x]>ptr0[x])&&(ptr1[x]>ptr2[x])&&(ptr1[x]>thres))||((
ptr1[x]>ptr1[x-
3])&&(ptr1[x]>ptr1[x+3])&&(ptr1[x]>thres))//si el medio es
mas grande bueno segundo con truco

```

```

    {
        ptr3[x]=255;
        ptr3[x+1]=255;
        ptr3[x+2]=255;
    }
    else
    {
        ptr3[x]=1;
        ptr3[x+1]=1;
        ptr3[x+2]=1;
    }
}

if(sector==3)
{
    if((ptr1[x]>ptr0[x-3])&&(ptr1[x]>ptr2[x+3])&&(ptr1[x]>thres))//si el medio es mas grande
        //if((ptr1[x]>ptr2[x-3])&&(ptr1[x]>ptr0[x+3])&&(ptr1[x]>thres))//si el medio es mas grande
        {
            ptr3[x]=255;
            ptr3[x+1]=255;
            ptr3[x+2]=255;
        }
        else
        {
            ptr3[x]=1;
            ptr3[x+1]=1;
            ptr3[x+2]=1;
        }
    }
    x=x+2;
} //fin x
} //fin y
//salva a imagenes de bordes
if(img==1)
{
    Lienzo1->Canvas->Draw(0,0,pBitmap3->Bitmap);
    pBitmap3->SaveToFile("Img1s.bmp");
}
if(img==2)
{
    Lienzo2->Canvas->Draw(0,0,pBitmap3->Bitmap);
    pBitmap3->SaveToFile("Img2s.bmp");
}
} //finaliza canny

delete pBitmap;
delete pBitmap2;
delete pBitmap3;
}
//-----
---
void TForm1::Hough(int img)
{
    Graphics::TPicture *pBitmap = new Graphics::TPicture();
    int cx,cy,x,y,x2,y2;
    int max_rad=600; //radio maximo
    float angulo,angulo2,m;
    int r,t,t2;
    int val_div=thres_z*4; //valor division
    float incr_ang;
    int umbral_car; //umbral de no. características

    if(img==1){
        //Errors->Lines->Clear();
        pBitmap->Bitmap->LoadFromFile("Img1g.bmp");

        Lienzo3->Canvas->Draw(0,0,pBitmap->Bitmap);
        pBitmap->Bitmap->LoadFromFile("Img1s.bmp");
    }
    if(img==2){
        pBitmap->Bitmap->LoadFromFile("Img2g.bmp");
        Lienzo4->Canvas->Draw(0,0,pBitmap->Bitmap);
        pBitmap->Bitmap->LoadFromFile("Img2s.bmp");
    }

    pBitmap->Bitmap->PixelFormat=pf24bit,pf24bit;

    for(int k=0;k<max_img_y;k++) //inicializa super
    arreglo a 0
    {
        for(int l=0;l<max_img_x;l++)
        {
            for(t=0;t<thres_z*2;t++)
            {
                s_arr[0][l][k][t]=false;
                s_arr[1][l][k][t]=false;
            }
        }
    }

    for(t=0;t<361;t++) //inicializa arreglo a 0
    {
        for(r=0;r<max_rad;r++)
            arreglo[t][r]=0;
    }
    //centro de la imagen
    cy=pBitmap->Bitmap->Height/2;
    cx=pBitmap->Bitmap->Width/2;

    //dibuja ejes no es necesario correr ya lo posiciona
    DrawLinea(0,0,0,-100,0,255,0,pBitmap,(img+2));
    DrawLinea(0,0,100,0,0,255,0,pBitmap,(img+2));
    DrawLinea(0,0,0,100,0,255,0,pBitmap,(img+2));
    DrawLinea(0,0,-100,0,0,255,0,pBitmap,(img+2));

    img--; //para poner en super arreglo las características
    incr_ang=(2.0*M_PI)/val_div;
    //obtiene características y las suma en el arreglo
    for (int j = 0; j < pBitmap->Bitmap->Height-1; j++)
    {
        ptr = (Byte *)pBitmap->Bitmap->ScanLine[j];

        x=-cx;
        y=cy-j;
        for (int i = 0; i < ((pBitmap->Bitmap->Width)*3)-3; i++)
        {
            x++;
            if(ptr[i]==255) //si es uno(característica)
            {
                angulo=0.0;
                for(int ciclo=1;ciclo<=val_div/2;ciclo++) //ciclo angulo
                de .1 a 180
                {
                    //angulo=((2.0*M_PI)/val_div)*ciclo; //angulo del
                    vector en rad
                    angulo+=incr_ang; //para que las operaciones
                    sean sumas
                    get_pol(x,y,angulo,pBitmap); //obtiene polares con x,y
                    cartesianas
                }
            } //si es borde
            i+=2;
        } //end x
    } //end y
    //Lienzo3->Repaint();
    //Lienzo4->Repaint();
}

```

```

//idea: hacer una segunda pasada donde si el # car es mayor
enonces ponga tambien en s arr
umbral_car=(sqrt((pBitmap->Bitmap->Height)*(pBitmap->
Bitmap->Width)))/thres_h;

for (int j = 0; j < pBitmap->Bitmap->Height-1; j++)
{
ptr = (Byte *)pBitmap->Bitmap->ScanLine[j];
//Status->SimpleText=" "+FloatToStr(j)+" |
"+((j*100)/(pBitmap->Bitmap->Height))+"%"; //escribe
porcentaje de imagen realizada
x=-cx;
y=cy-j;
for (int i = 0; i < ((pBitmap->Bitmap->Width)*3)-3; i++)
{
x++;
if(ptr[i]==255) //si es uno(característica)
{

angulo=0.0;
for(int ciclo=1;ciclo<=val_div/2;ciclo++) //ciclo angulo
de .1 a 180
{
//angulo=((2.0*M_PI)/val_div)*ciclo; //angulo del
vector en rad
angulo+=incr_ang;

get_rt(x,y,angulo,pBitmap);//obteine r y t en variables tet
y rad
//if(ciclo==0)r=abs(y);
if(arreglo[tet][rad]>umbral_car)
{
s_arr[img][i/3][j][ciclo-1]=true; //si es mayor al
umbral pone
//Errors->Lines->Add("imagen:" +IntToStr(img)+"|
X:" +IntToStr(x)+"| Y:" +IntToStr(y)+"|
Angulo:" +IntToStr(((360/val_div)*ciclo));
if(PintaBorde1->Checked==true)
{
if(img==0)polar(rad,tet,pBitmap,1);
if(img==1)polar(rad,tet,pBitmap,2);
}

//pintado de los detectados quitar para rapidez
//if(img==0)Lienzo3->Canvas->Pixels[x+cx][cy-
y]=0xff0000;
//if(img==1)Lienzo4->Canvas->Pixels[x+cx][cy-
y]=0xff0000;
}
} //end si es borde
i+=2;
} //end x
//Lienzo3->Repaint();
//Lienzo4->Repaint();
} //end y

//Errors->Lines->SaveToFile("out.txt");
if(img==2){
//Errors->Lines->Clear();

}

delete pBitmap;
}
//-----
---
```

```

void TForm1::Matching() //obtiene pares de características
similares
{
Graphics::TPicture *pBitmap = new Graphics::TPicture();
Graphics::TPicture *pBitmap2 = new Graphics::TPicture();

Graphics::TPicture *pBitmapG = new Graphics::TPicture();
Graphics::TPicture *pBitmap2G = new Graphics::TPicture();

int car1[255],car2[255],c1=0,c2=0;j; //arreglo
características y puntero int menor_arr;
int menor_carac,result; //major y actual match

iniimg2(pBitmap,pBitmap2); //carga imagen binaria
en pbitmap y pbitmap2

pBitmapG->Bitmap->LoadFromFile("Img1g.bmp");
pBitmap2G->Bitmap->LoadFromFile("Img2g.bmp");

pBitmapG->Bitmap->PixelFormat=pf24bit,pf24bit;
pBitmap2G->Bitmap->PixelFormat=pf24bit,pf24bit;

//inicializacion arreglo de match pairs
for(int ciclo=0;ciclo<512;ciclo++)
{
pares[ciclo][0]=0;
pares[ciclo][1]=0;
pares[ciclo][2]=0;
pares[ciclo][3]=0;
}
ptr_pares=0;

Errors->Lines->Clear();
for (int y = 1; y < pBitmap->Bitmap->Height-1;
y=y+thres_lin) //recorrido cada y lineas
//hace recorrido solo sobre una sola línea
//for (int y = pBitmap->Bitmap->Height/2; y < (pBitmap->
Bitmap->Height/2)+1; y++)
{
ptr = (Byte *)pBitmap->Bitmap->ScanLine[y];
ptr2 = (Byte *)pBitmap2->Bitmap->ScanLine[y];

ptr0 = (Byte *)pBitmapG->Bitmap->ScanLine[y];
ptr1 = (Byte *)pBitmap2G->Bitmap->ScanLine[y];
j=0;
c1=0;
c2=0;
//pone en un arreglo las características imagen derecha e izq
for (int x = 3; x < ((pBitmap->Bitmap->Width)*3)-6; x++)
{
j++;
if(ptr[x]==255)
{
car1[c1]=j;//arreglo imagenes izq
c1++;
Errors->Lines->Add("Car1:" +IntToStr(j));
}
if(ptr2[x]==255)
{
car2[c2]=j;//arreglo imagenes der
c2++;
Errors->Lines->Add("Car2:" +IntToStr(j));
}

x=x+2;
}
//Status->SimpleText=IntToStr(c1)+" "+c2+" yes:" +y;

```

```

    if((c1==c2)&&(c1>0)&&(c2>0))//si arreglos tienen igual
longitud
    {
        for(int ciclo1=0;ciclo1<c1;ciclo1++)
        {
            Errors->Lines->Add("xi:"+IntToStr(car1[ciclo1])+")
            yi:"+y+"| xd:"+car2[ciclo1]+") yd:"+y+"
            #pix="+(car1[ciclo1]-car2[ciclo1]);//izquierdo-derecho
        }

        if((c2!=c1)&&(c1>0)&&(c2>0))
        {
            //quita las características no compatibles inclinación y gris
            //asociacion con el mas similar (menor diferencia y menor a
            threshold)
            if(c1<c2) //si la izquierda tiene menos
            {
                for(int ciclo1=0;ciclo1<c1;ciclo1++)
                {
                    menor_carac=10000;
                    for(int ciclo2=0;ciclo2<c2;ciclo2++)
                    { //ptr[car1[ciclo1],ptr2[car2[ciclo2]]
                        result=diferencia(ptr0[((car1[ciclo1])*3)-
                        3],ptr0[(car1[ciclo1])*3],ptr0[((car1[ciclo1])*3)+3],ptr1[((car2
                        [ciclo2])*3)-
                        3],ptr1[(car2[ciclo2])*3],ptr1[((car2[ciclo2])*3)+3],car1[ciclo1
                        ],car2[ciclo2],y,1);
                        if(result<menor_carac)
                        {
                            //asigna a arreglo
                            pares[ ptr_pares][0]=car1[ciclo1];
                            pares[ ptr_pares][1]=y;
                            pares[ ptr_pares][2]=car2[ciclo2];
                            pares[ ptr_pares][3]=y;
                            menor_carac=result;
                        }
                    }
                }
                Errors->Lines-
                >Add("xi:"+IntToStr(pares[ptr_pares][0])+") yi:"+y+"|
                xd:"+pares[ptr_pares][2]+") yd:"+y+"
                #pix="+(pares[ptr_pares][0]-pares[ ptr_pares][2]);//izquierdo-
                derecho
                ptr_pares++; //incrementa para siguiente match
            }
            else //(c2<c1) //si la derecha tiene menos
            {
                for(int ciclo2=0;ciclo2<c2;ciclo2++)
                {
                    menor_carac=10000;
                    for(int ciclo1=0;ciclo1<c1;ciclo1++)
                    {
                        result=diferencia(ptr0[((car1[ciclo1])*3)-
                        3],ptr0[(car1[ciclo1])*3],ptr0[((car1[ciclo1])*3)+3],ptr1[((car2
                        [ciclo2])*3)-
                        3],ptr1[(car2[ciclo2])*3],ptr1[((car2[ciclo2])*3)+3],car1[ciclo1
                        ],car2[ciclo2],y,1);
                        if(result<menor_carac)
                        {
                            //asigna a arreglo
                            pares[ ptr_pares][0]=car1[ciclo1];
                            pares[ ptr_pares][1]=y;
                            pares[ ptr_pares][2]=car2[ciclo2];
                            pares[ ptr_pares][3]=y;
                            menor_carac=result;
                        }
                    }
                }
                Errors->Lines-
                >Add("xi:"+IntToStr(pares[ptr_pares][0])+") yi:"+y+"

```

```

            xd:"+pares[ptr_pares][2]+") yd:"+y+"
            #pix="+(pares[ptr_pares][0]-pares[ ptr_pares][2]);//izquierdo-
            derecho
            ptr_pares++; //incrementa para siguiente match
        }
    } // si ya esta normalizado (cada uno con un par)
} //fin y

dosDtotesD(pBitmap);

delete pBitmap;
delete pBitmap2;

delete pBitmapG;
delete pBitmap2G;
}
//-----
void __fastcall TForm1::Camara1Click(TObject *Sender)
{
    //intento de configuracion de la camara
    Video->Dialogs;

    //Video->ShowDialog();
    //Video->InsertControl();
    //Video->Controls();
    //Video->GetInterface();
    //Video->
}
//-----
void __fastcall TForm1::Calibracion1Click(TObject *Sender)
{
    FormCalibration=new TFormCalibration (Application);
    FormCalibration->ShowModal();
    delete FormCalibration;
}
//-----
void __fastcall TForm1::Extra3DClick(TObject *Sender)
{
    FormTresD = new TFormTresD ( Application);
    FormTresD->ShowModal();
    //FormTresD->Close();
    delete FormTresD;
}
//-----
void __fastcall TForm1::SigmoidalClick(TObject *Sender)
{
    if(Sigmoidal->Checked==true)
    {
        Sigmoidal->Checked=false;
    }
    else
    {
        Sigmoidal->Checked=true;
    }
}
//-----
void __fastcall TForm1::FiltradoONClick(TObject *Sender)
{
    if(FiltradoON->Checked==true)
        FiltradoON->Checked=false;
    else
        FiltradoON->Checked=true;
}

```

```

//-----
-
void __fastcall TForm1::GaussianoClick(TObject *Sender)
{
    if(Gaussiano->Checked==true)
        Gaussiano->Checked=false;
    else
        Gaussiano->Checked=true;
}
//-----
-
void __fastcall TForm1::BordeCanny1Click(TObject *Sender)
{
    if(BordeCanny1->Checked==true)//inicializacion sobel
    {
        BordeCanny1->Checked=false;

        thres=52; //threshold binarizacion
        thres_h=5; //threshold tamaño de no muestras para
        hough
        thres_z=8; //threshold zonas de hough
        thres_c=5000;

        //mascara sobel 3x3
        sx[1][1]=-1.0;
        sx[1][2]=0.0;
        sx[1][3]=1.0;
        sx[2][1]=-2.0;
        sx[2][2]=0.0;
        sx[2][3]=2.0;
        sx[3][1]=-1.0;
        sx[3][2]=0.0;
        sx[3][3]=1.0;

        sy[1][1]=1.0;
        sy[1][2]=2.0;
        sy[1][3]=1.0;
        sy[2][1]=0.0;
        sy[2][2]=0.0;
        sy[2][3]=0.0;
        sy[3][1]=-1.0;
        sy[3][2]=-2.0;
        sy[3][3]=-1.0;
    }
    else //inicializacion cuando corra canny
    {
        BordeCanny1->Checked=true;
        //anteriormente 20,8,15
        thres=20; //threshold binarizacion
        thres_h=7; //threshold tamaño de no muestras para
        hough
        thres_z=20; //threshold zonas de hough
        thres_c=5000;

        sx[1][1]=1.0;
        sx[1][2]=0.0;
        sx[2][1]=0.0;
        sx[2][2]=-1.0;

        sy[1][1]=0.0;
        sy[1][2]=-1.0;
        sy[2][1]=1.0;
        sy[2][2]=0.0;
    }
}
//-----
---
void __fastcall TForm1::PintaBorde1Click(TObject *Sender)
//Dibuja vectores
{

```

```

    if(PintaBorde1->Checked==true)
        PintaBorde1->Checked=false;
    else
        PintaBorde1->Checked=true;
}
//-----
---
void __fastcall TForm1::CaracteristClick(TObject *Sender)
{ //Despliega pantalla con el matching
    if(Caracterist->Checked==true)
    {
        Caracterist->Checked=false;
        Errors->Visible=false;
    }
    else
    {
        Caracterist->Checked=true;
        Errors->Visible=true;
    }
}
//-----
-
void __fastcall TForm1::noajusteClick(TObject *Sender)
{
    if(noajuste->Checked==false)
    {
        exponencial->Checked=false;
        polinomio->Checked=false;
        noajuste->Checked=true;
    }
}
//-----
-
void __fastcall TForm1::exponencialClick(TObject *Sender)
{
    if(exponencial->Checked==false)
    {
        exponencial->Checked=true;
        polinomio->Checked=false;
        noajuste->Checked=false;
    }
}
//-----
-
void __fastcall TForm1::polinomioClick(TObject *Sender)
{
    if(polinomio->Checked==false)
    {
        exponencial->Checked=false;
        polinomio->Checked=true;
        noajuste->Checked=false;
    }
}
//-----
-
void __fastcall TForm1::OGLButtonClick(TObject *Sender)
{
    FormTresD = new TFormTresD (Application);
    FormTresD->ShowModal();
    //FormTresD->Close();
    delete FormTresD;
}
//-----
-
void __fastcall TForm1::Salir1Click(TObject *Sender)
{

```

```
    Close();
}
//-----
---
void __fastcall TForm1::CloseButtonClick(TObject *Sender)
{
    Close();
}
//-----
-
void __fastcall TForm1::FormDestroy(TObject * Sender)
{
```

```
    delete config;
}
//-----
---
void __fastcall TForm1::FormClose(TObject *Sender,
TCloseAction & Action)
{
    Video->StopPreview();
}
//-----
---
//Status->SimpleText=IntToStr(thres)
```